<table>
<thead>
<tr>
<th>Registration No.</th>
<th>Number 00118</th>
</tr>
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<tbody>
<tr>
<td>Registration Date</td>
<td>September 10, 2013</td>
</tr>
<tr>
<td>Registration Category</td>
<td>Category 1</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Name (Model, etc.)</th>
<th>FANUC ROBOT MODEL1</th>
</tr>
</thead>
<tbody>
<tr>
<td>Location</td>
<td>Oshino Village, Minamitsuru District, Yamanashi Pref</td>
</tr>
<tr>
<td>Owner (Custodian)</td>
<td>FANUC CORPORATION</td>
</tr>
<tr>
<td>Manufacturer (Company)</td>
<td>FANUC CORPORATION</td>
</tr>
<tr>
<td>Year Manufactured</td>
<td>1977</td>
</tr>
<tr>
<td>Year First Appeared</td>
<td>1977</td>
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<tr>
<td>Reason For Selection</td>
<td>These industrial robots made significant price reductions a reality and turned Japan into the robot superpower it is today. These PTP-controlled robots with five degrees of freedom and a cylindrical coordinate system were used for detaching and attaching multiple CNC machine tool workpieces placed around them, operating by positioning and orienting the finger parts within a cylindrical space. The arms moved on three axes – up and down, forwards and backwards and rotational – controlled by DC servo motors, while the finger parts moved on two axes, controlled by pneumatic pressure. The servo motors were controlled by switching a single control circuit to operate multiple servo motors, a simultaneous single-axis control system.</td>
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<tr>
<td>Registration Standard</td>
<td>1 - A , 2 - B</td>
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<table>
<thead>
<tr>
<th>Open/Closed to Public</th>
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<tr>
<td>Photo</td>
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| Other useful information | |
|--------------------------| |